Part number:



HYDRAULICKÉ SYSTÉMY



UKŁADY HYDRAULICZNE



RE 29115/08.13 Replaces: 10.05

Electric Drives and Controls

Hydraulics

Linear Motion and Assembly Technologies

Pneumatics

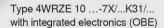
Service

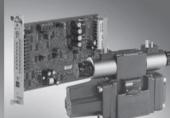
4/2, 4/3, and 5/2, 5/3 proportional directional valve, pilot operated, without electrical position feedback without/with integrated electronics (OBE)

Type .WRZ..., .WRZE... and .WRH...

Sizes 10 to 52 Component series 7X Maximum operating pressure 350 bar Maximum flow 2800 l/min







Type 4WRZ 10 ...-7X/...K4/... with the corresponding control electronics (separate order)

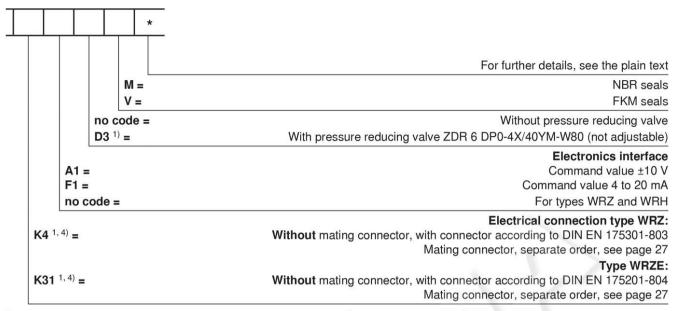
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Features

- Pilot operated, 2-stage proportional directional valve with integrated electronics (OBE) with type 4WRZE
- Control of flow direction and size
- Operation by means of proportional solenoids with central thread and detachable coil
- For subplate mounting:
 - Porting pattern according to ISO 4401
- Manual override, optional
- Spring-centered control spool
- Control electronics
 - Type .WRZE...
 - Integrated electronics (OBE) with voltage or current input (A1 and/or F1)
 - Type .WRZ...
 - Digital or analog amplifier in Euro-card format
 - Analog amplifier in modular design

| | awp. | | -x 1/ | |
|--|---------------------|--------------|---------|--------------------------|
| | 4WR_ | | 7X / | |
| | | | | |
| Hydraulic actuation | = H | | | |
| Electro-hydraulic actuation | = Z | | | |
| Type WRZ: | | | | |
| For external electronics | = no code | | | |
| With integrated electronics | = E | | | |
| Size 10 | = 10 |) | | |
| Size 16 | = 16 | 6 | | |
| Size 25 | = 25 | 6 I I I | | |
| Size 32 | = 32 | | | |
| Size 52 | = 52 | 2 | | |
| For control spool symbols , see page 3 | | | | |
| Rated flow in I/min at valve pressure differential 2 | 1 p = 10 bar | | | |
| Size 10 | | | | |
| 25 l/min | | = 25 | 1 1 1 | |
| 50 l/min | | = 50 = 85 | | |
| 85 l/min Size 16 | | = 65 | | |
| 100 l/min | | = 100 | | |
| 125 l/min | | = 125 | | |
| 150 l/min | | = 150 | | |
| 180 l/min | | = 180 | | |
| | | = 180 | | |
| Size 25 220 l/min | | = 220 | | |
| 325 l/min | | = 325 | | |
| Size 32 | | _ 020 | | |
| 360 l/min | | = 360 | | |
| 520 l/min | | = 520 | | |
| Size 52 | | | | |
| 1000 l/min | | = 1000 | | |
| Component series 70 to 79 | | = 7) | (| |
| (70 to 79: Unchanged installation and connection | dimensions) | | _ | |
| For subplate mounting | | = no | code | |
| For flange connection (size 52 only) | | | = F | |
| Pilot control valve size 6 | | | - | |
| Proportional solenoid with detachable coil | | | = 6E 1) | |
| Supply voltage | | | | |
| Direct voltage 24 V | | | = G: | 24 1) |
| Without manual override | | | 8 | = no code |
| With concealed manual override | | | | = N9 ^{1, 2)} |
| Without special type of protection | | | | = no code |
| Seawater-resistant | | | | = J ³⁾ |
| Pilot oil supply and return | | | | |
| External pilot oil supply, external pilot oil return | | | | = no coo |
| Internal pilot oil supply, external pilot oil return | | | | = |
| Internal pilot oil supply, internal pilot oil return | | | | = E |
| External pilot oil supply, internal pilot oil return | | | | = |
| (only possible without code for size 52 and type 4) | WRH) | | | |

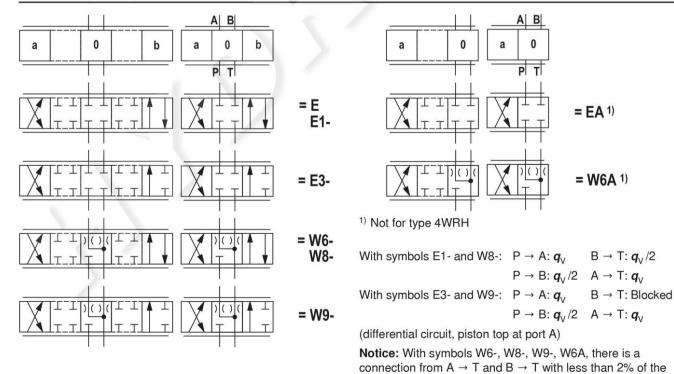


¹⁾ Not applicable with types 4WRH

respective nominal cross-section in switching position "0".

Electric special types of protection available on request.

Control spool symbols

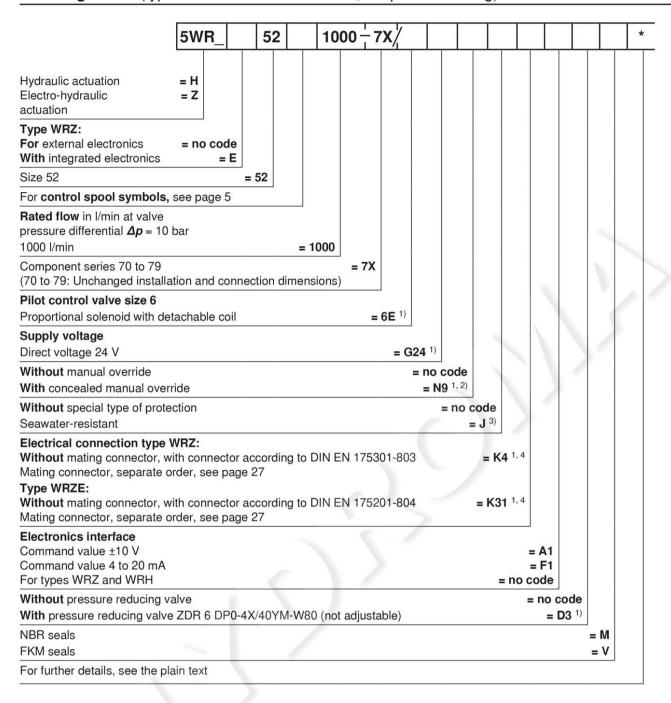


²⁾ For version "J"→"N" instead of "N9"

³⁾ For information on the seawater-resistant version, see data sheet 29115-M

⁴⁾ For version "J" = seawater-resistant only "K31"

Ordering codes (types 4WRZ 52 and 4WRH 52; subplate mounting)



¹⁾ Not applicable with types 4WRH

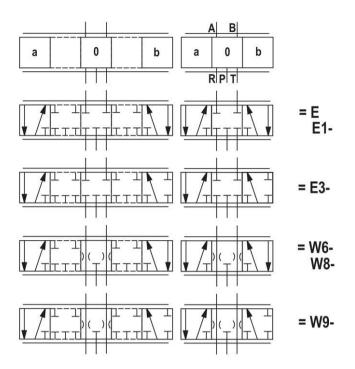
Electric special types of protection available on request.

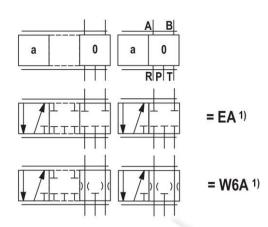
²⁾ For version "J"→"N" instead of "N9"

³⁾ For information on the seawater-resistant version, see data sheet 29115-M

⁴⁾ For version "J" = seawater-resistant only "K31"

Control spool symbols





1) Not for type 4WRH

With symbols E1- and W8-: $P \rightarrow A$: $q_V = B \rightarrow T$: $q_V/2$

 $P \rightarrow B: \boldsymbol{q}_V/2 \quad A \rightarrow R: \boldsymbol{q}_V$

With symbols E3- and W9-: $P \rightarrow A$: $q_V \rightarrow B \rightarrow T$: Blocked

 $P \rightarrow B: q_V/2 \quad A \rightarrow R: q_V$

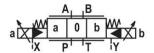
(differential circuit, piston top at port A)

Notice:

- Only external pilot oil supply and return possible
- With control spool W6-, W8-, W9-, W6A, there is a connection from A → R and B → T with less than 2% of the respective nominal cross-section in switching position "0".

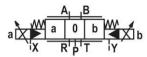
With electro-hydraulic actuation and for external electronics

Type 4WRZ...-7X./... and type 4WRZ 52...-7XF/...



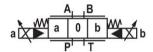
X = external Y = external

Type 5WRZ 52-7X./...

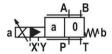


X = external Y = external

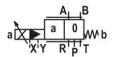
Type 4WRZ...-7X./...ET...



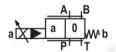
X = internalY = internal Type 4WRZ...A-7X./... and type 4WRZ 52 A...-7XF/...



Type 5WRZ 52 A-7X./...

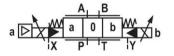


Type 4WRZ.A...-7X./...ET...



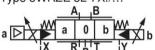
With electro-hydraulic actuation and for integrated electronics

Type 4WRZE...-7X./... and type 4WRZE 52...-7XF/...



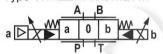
X = external Y = external

Type 5WRZE 52-7X./...

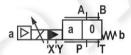


X = external Y = external

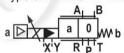
Type 4WRZE...-7X./...ET...



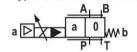
X = internal Y = internal Type 4WRZE...A-7X./... and type 4WRZE 52 A...-7XF/...



Type 5WRZE 52 A-7X./...

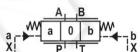


Type 4WRZE.A...-7X./...ET...

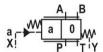


With hydraulic actuation

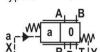
Type 4WRH...-7X./... and type 4WRH 52...-7XF/...



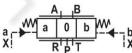
X = external Y = external Type 4WRH...A...-7X./... and type 4WRH 52...-7XF/...



Type 5WRH 52 A...-7X./...



| Туре | 5WRH | 52 | 7X |
|------|------|----|----|
|------|------|----|----|



X = external Y = external

Pilot control valve type 3DREP 6...

The pilot control valve is a 3-way pressure reducing valve that is actuated by a proportional solenoid. It converts an electrical input signal into a proportional pressure output signal and is used for all valves of the type 4WRZ... and 5WRZ...

The proportional solenoids are controllable, wet-pin DC solenoids with a central thread and a detachable coil. The solenoids are controlled by external electronics (type .WRZ...).

Set-up:

The valve basically consists of:

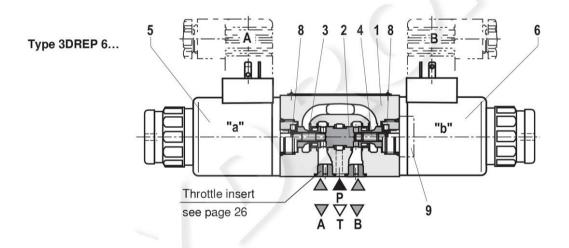
- Housing (1)
- Control spool (2) with pressure measuring spool (3 and 4)
- Solenoids (5 and 6) with central threads

Function:

The pressure in A or B is set by means of the proportional solenoids. The amount of the pressure depends on the current. With de-energized solenoids (5, 6), the control spool (2) is held in the central position by means of the pressure springs (8). Ports A and B are connected with T so that the hydraulic fluid can flow to the tank without obstructions.

By energizing a proportional solenoid, e.g. solenoid "a" (5), the pressure measuring spool (3) and with it the control spool (2) are moved to the right. This opens the connection from P to B and A to T via orifice-type cross-sections with progressive flow characteristic. With the surface of the pressure measuring spool (4) the pressure that builds up in channel B acts on the control spool and against the solenoid force. The pressure measuring spool (4) is supported by solenoid "b". If the pressure exceeds the value set at solenoid "a", the control spool (2) is pushed back against the solenoid force and connects B with T until the set pressure is reached again. The pressure is proportional to the solenoid current. When the solenoid is switched off, the control spool (2)

When the solenoid is switched off, the control spool (2) is returned into the central position by the compression springs (8).



Pilot control valve with two switching positions (type 3DREP 6...B...)

The operation of this valve version basically corresponds to the valve with 3 switching positions. However, this 2 spool position valve is only equipped with solenoid "a" (5). In the place of the second proportional solenoid there is a plug screw (9).

Information on type 3DREP 6:

Prevent the tank line from draining. If this is possible due to installation conditions, install a preload valve (with a preload pressure of approx. 2 bar).

Pilot control valve type 3DREPE 6...

The pilot control valve is a 3-way pressure reducing valve that is actuated by a proportional solenoid. It converts an electrical input signal into a proportional pressure output signal and is used for all valves of the type 4WRZE... and 5WRZE...

The proportional solenoids are controllable, wet-pin DC solenoids with a central thread and a detachable coil. The solenoids are controlled by the integrated electronics (type .WRZE...).

Set-up:

The valve basically consists of:

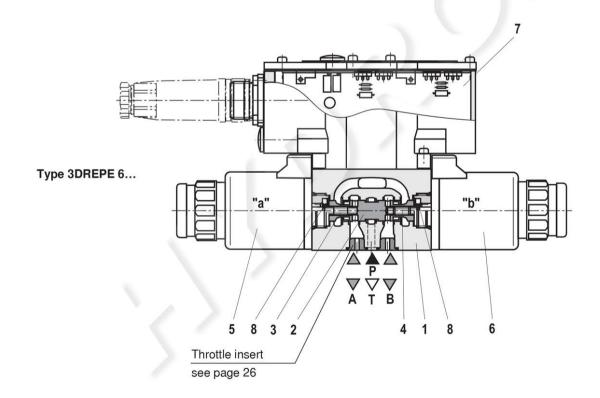
- Housing (1)
- Control spool (2) with pressure measuring spool (3 and 4)
- Solenoids (5 and 6) with central threads
- Integrated electronics (7)

Function:

The pressure in A or B is set by means of the proportional solenoids. The amount of the pressure depends on the current. With de-energized solenoids (5, 6), the control spool (2) is held in the central position by means of the pressure springs (8). Ports A and B are connected with T so that the hydraulic fluid can flow to the tank without obstructions.

By energizing a proportional solenoid, e.g. solenoid "a" (5), the pressure measuring spool (3) and with it the control spool (2) are moved to the right. This opens the connection from P to B and A to T via orifice-type cross-sections with progressive flow characteristic. With the surface of the pressure measuring spool (4) the pressure that builds up in channel B acts on the control spool and against the solenoid force. The pressure measuring spool (4) is supported by solenoid "b". If the pressure exceeds the value set at solenoid "a", the control spool (2) is pushed back against the solenoid force and connects B with T until the set pressure is reached again. The pressure is proportional to the solenoid current.

When the solenoid is switched off, the control spool (2) is returned into the central position by the compression springs (8).



Pilot operated proportional directional valves Types 4WRZ... and 5WRZ.52...

Valves of type 4WRZ... are pilot operated 4-way directional valves that are actuated by proportional solenoids. They control the flow direction and size.

Valves of type 5WRZ... are equipped with an additional port "R" (only size 52).

Set-up:

The valve basically consists of:

- Pilot control valve (9) with proportional solenoids (5 and 6)
- Main valve (10) with main control spool (11) and centering spring (12)

Notice!

Due to the design principle, internal leakage is inherent to the valves, which may increase over the life cycle.

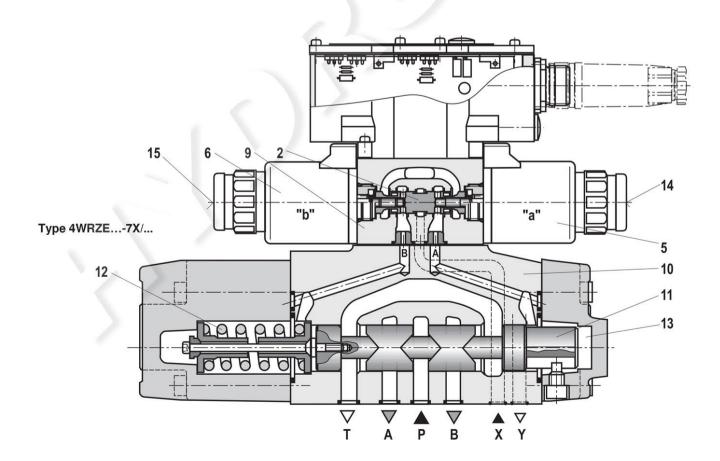
Function:

- With de-energized solenoids (5, 6), the main control spool (11) is held in the central position by means of the centering spring (12).
- The main control spool (11) is controlled by the pilot control valve (9); the main control spool is proportionally moved, e.g. by actuating solenoid "b" (6).
 - → The control spool (2) is moved to the right, pilot oil enters the pressure chamber (13) via the pilot control valve (9) and deflects the main control spool (11) according to the electric input signal.
 - → This opens the connection from P to B and A to T via orifice-type cross-sections with progressive flow characteristic.
- Pilot oil is internally supplied to the pilot control valve via port P or externally via port X.
- Switching the solenoid off (6)
 - → The control spool (2) and main control spool (11) are moved back into the central position.
- Depending on the switching position, flow occurs from P to A and B to T or P to B and A to T (R).

An optional manual override (14 and 15) can be used to move the control spool (2) without solenoid energization.

Notice:

Inadvertent activation of the manual override may result in uncontrollable machine movements.



Externally pilot operated proportional directional valves Types 4WRH... and 5WRH.52...

Valves of the type .WRH... are pilot operated proportional directional valves for external actuation via pressure control valves.

Set-up:

The valve basically consists of:

- Main valve (10) with main control spool (11) and centering spring (12)
- Diversion plate (16)

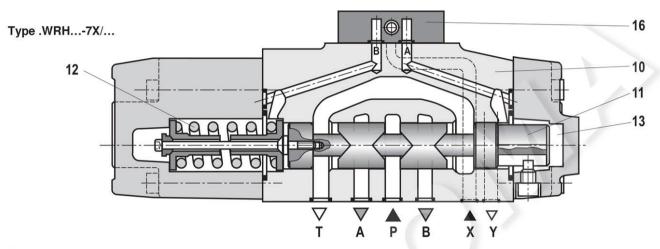
Notice!

Due to the design principle, internal leakage is inherent to the valves, which may increase over the life cycle.

Function:

- The diversion plate (16) connects control port A that leads to the pressure chamber (13) with port Y and control port B with port X.
- If port X is pressurized, the main control spool (11) is moved to the right (P to B and A to T). If port Y is pressurized, the main control spool is moved to the left (P to A and B to T).

The pilot pressure at the main valve must not exceed 25 bar (16 bar with size 52)!



Technical data (for applications outside these parameters, please consult us!)

general .WRZ .WRZE .WRH Valve type Installation position Any, preferably horizontal (for commissioning information, see data sheet 07800) °C -20 to +80 Storage temperature range Ambient temperature range °C -20 to +70 -20 to +50 -20 to +70 Weight - Subplate mounting Size 10 kg 7.8 8.0 6.1 Size 16 11.9 12.1 9.7 kg Size 25 18.2 18.4 18.0 kg Size 32 42.2 42.2 41.5 kg Size 52 kg 79.5 79.7 Size 52 77.5 77.7 - Flange connection kg - With "D3" +0.5 in addition kg Sine test according to DIN EN 60068-2-6:2008 10 cycles, 10...2000...10 Hz with logarithmic frequency changing speed of 1 oct./min., 5 to 57 Hz, amplitude 1.5 mm (p-p), 57 to 2000 Hz, amplitude 10 g, 3 axes 20...2000 Hz, amplitude 0.05 g²/Hz (10 g_{RMS}) Random test according to DIN EN 60068-2-64:2009 3 axes, 30 min testing time per axis Shock test according to DIN EN 60068-2-27:2010 Half sine 15 g/11 ms, 3 times in positive/3 times in negative direction per axis, 3 axes Variant 2 Humid heat, cyclic according to DIN EN 60068-2-30:2006 +25 °C to +55 °C, 90% to 97% relative humidity, 2 cycles at 24 hours each

Technical data (for applications outside these parameters, please consult us!)

hydraulic (measured with HLP46, $\vartheta_{\text{oil}} = 40 \, ^{\circ}\text{C} \pm 5 \, ^{\circ}\text{C}$ and $p = 100 \, \text{bar}$) Size 25 32 52 Operating pressure - Pilot control valve External pilot oil supply 30 to 100 20 to 100 bar Internal pilot oil supply 100 to bar 315 only 100 to 350 only with "D3" with "D3" Up to 350 - Main valve bar Up to 315 Up to 350 Up to 350 Up to 350 Up to 250 Up to 250 Return flow pressure - Port T (port R) Up to 315 Up to 250 Up to 150 bar (external pilot oil return) - Port T Up to 30 Up to 30 Up to 30 bar Up to 30 (internal pilot oil return) - Port Y bar Up to 30 Flow of the main valve I/min Up to 170 Up to 460 Up to 870 Up to 1600 Up to 2800 Pilot flow at ports X and Y I/min 3.5 5.5 7 15.9 7 with stepped input signal 0 → 100% Pilot volume cm^3 1.7 4.6 10 26.5 54.3 for switching process 0 → 100% Hydraulic fluid See table below -20 to +80 (preferably +40 to +50) Hydraulic fluid temperature range (at the valve working ports) Viscosity range mm²/s 20 to 380 (preferably 30 to 46) Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c) - Pilot control valve Class 18/16/13 1) Class 20/18/15 1) - Main valve % Hysteresis ≤ 6

¹⁾ The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components.
For the selection of the filters, see www.boschrexroth.com/filter

| Hydraulic fluid | Classification | Suitable sealing materials | Standards |
|---------------------------------------|---|----------------------------|-----------|
| Mineral oils and related hydrocarbons | HL, HLP | NBR, FKM | DIN 51524 |
| Flame-resistant – containing water | HFC (Fuchs HYDROTHERM 46M, Petrofer Ultra Safe 620) | NBR | ISO 12922 |

Important information on hydraulic fluids!

- For more information and data on the use of other hydraulic fluids refer to data sheet 90220 or contact us!
- There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.)!
- The flash point of the process and operating medium used must be 40 K greater than the maximum solenoid surface temperature.
- Flame-resistant containing water: The maximum pressure differential per control edge is 175 bar. Pressure preloading at the tank port > 20% of the pressure differential; otherwise, increased cavitation.
- Life cycle as compared to operation with mineral oil HL, HLP 50% to 100%

Technical data (for applications outside these parameters, please consult us!)

| electric | | | | |
|---|---------------------------------------|----------------|-----------------------------|--------------------|
| Valve type | | | .WRZ 1) | .WRZE |
| Voltage type | | Direct voltage | | |
| Command value overlap | | % | 15 | |
| Maximum current | | Α | 1.5 | 2.5 |
| Solenoid coil resistance | Cold value at 20 °C | Ω | 4.8 | 2 |
| | - Maximum hot value | Ω | 7.2 | 3 |
| Duty cycle % | | 100 | | |
| Maximum coil temperature ³⁾ °C | | 150 | | |
| Protection class of the valve | according to EN 60529 | | IP65 with mating connectors | mounted and locked |
| | | | * | |

Control electronics

| Type 4WRZ | Digital amplifier in Euro-card format 2) | | Digital amplifier in Euro-card format 2) VT-VSPD-1-2X/ according to data sheet 305 | |
|----------------------|--|----|--|----------------------------|
| | Analog amplifier in Euro-card format ²⁾ with 1 ramp time | | VT-VSPA2-1-2X/V0/T1, acco | ording to data sheet 30110 |
| | Analog amplifier in Euro-card format ²⁾ with 5 ramp times | | VT-VSPA2-1-2X/V0/T5, acco | ording to data sheet 30110 |
| | Analog module amplifier 2) | | VT-11118-1X/ according to | data sheet 30218 |
| Type 4WRZE | Analog command value module ²⁾ Analog command value module ²⁾ Digital command value card ²⁾ | | Integrated in the valve, see p | page 14 |
| | | | VT- SWMA-1-1X/ according to data sheet 29902 | |
| | | | VT-SWMAK-1-1X/ according to data sheet 29903 | |
| | | | VT-HACD-1-1X/ according | to data sheet 30143 |
| | Analog command value card ²⁾ | | VT-SWKA-1-1X/ according | to data sheet 30255 |
| Current consumption | I _{max} | Α | _ | 1.8 |
| | - Impulse current | Α | | 3 |
| Command value signal | - Voltage input "A1" | ٧ | _ | ±10 |
| | - Current input "F1" | nΑ | _ | 4 to 20 |

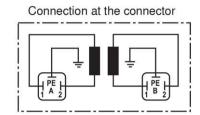
¹⁾ With Bosch Rexroth AG control electronics

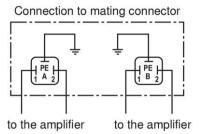
²⁾ Separate order

³⁾ Due to the temperatures occurring at the surfaces of the solenoid coils, the European standards ISO 13732-1 and EN 982 need to be adhered to.

Electrical connection

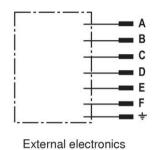
For type .WRZ... (for external electronics – not with version "J" = seawater-resistant)
For mating connectors, see page 27





 $\textbf{For type .WRZ...} \ (\textbf{for} \ \text{external electronics} - \text{with version "J"} = \text{seawater-resistant})$

For mating connectors, see page 27



| Contact | Connection with |
|---------|-----------------|
| A | Solenoid A |
| В | Solenoid B |
| С | Solenoid A |
| D | Solenoid B |
| E | n.c. |
| F | n.c. |
| PE | Valve housing |

For type .WRZE... (with integrated electronics (OBE) and with version "J" = seawater-resistant) For mating connectors, see page 27

| Connector pin assignment | Contact | Signal with A1 | Signal at F1 |
|--------------------------------|---------|--|-------------------------------------|
| Supply voltage | A | 24 VDC (u (t) = 19 | .4 to 35 V); I _{max} = 2 A |
| | В | | 0 V |
| Reference (actual value) | С | Cannot | be used 1) |
| Differential amplifier input | D | ±10 V; R _e > 50 kΩ | 4 to 20 mA; R_e > 100 Ω |
| (Command value) | E | Command value reference potential | |
| | F | Cannot be used 1) | |
| Protective grounding conductor | PE | Connected to cooling element and valve housing | |

¹⁾ Contacts C and F must not be connected!

Command value: A positive command value (0 to 10 V or 12 to 20 mA) at D and a reference potential at E result in a flow from P to A and B to T.

A negative command value (0 to -10 V or 12 to 4 mA) at D and a reference potential at E result in a flow from P to B and A to T.

If the valve and the solenoid are on side "a" (control spool variants EA and W6A), a positive command value at D and a reference potential at E result in flow from P to B and A to T.

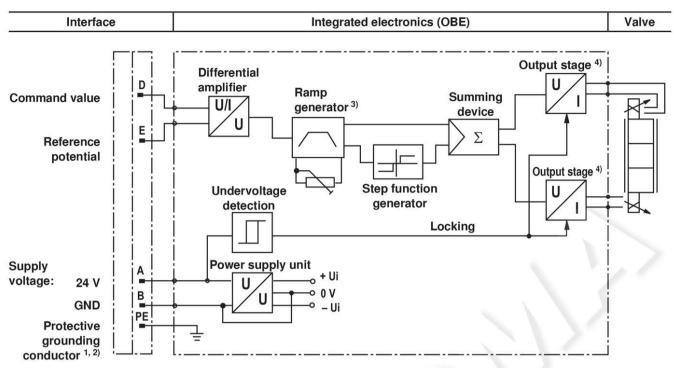
Connection cable: Recommendation: - Up to 25 m cable length, type LiYCY 5 x 0.75 mm²

- Up to 50 m 25 m cable length, type LiYCY 5 x 1.0 mm²

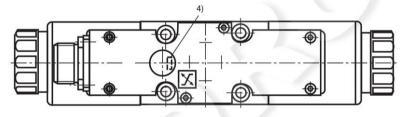
External diameter 6.5 to 11 mm

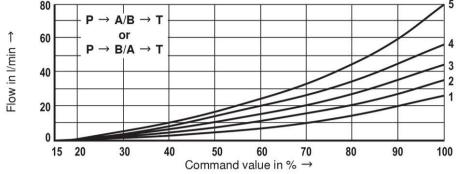
Only install the shield on the supply side on the protective grounding conductor.

Block diagram of the integrated electronics (OBE) for type WRZE

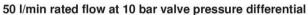


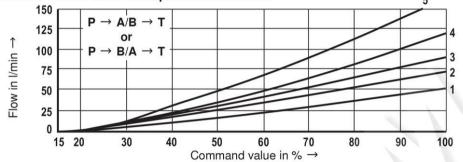
- 1) Port PE is connected to the cooling element and the valve housing
- ²⁾ The protective grounding conductor is screwed to the valve housing and cover
- $^{3)}$ Ramp can be set from 0 to 2.5 s from the outside, identical for $T_{\rm up}$ and $T_{\rm down}$
- 4) The output stages are current-controlled





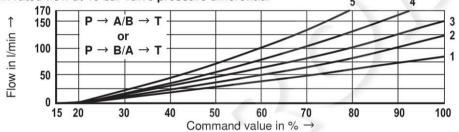
- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant





- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

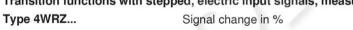
85 I/min rated flow at 10 bar valve pressure differential

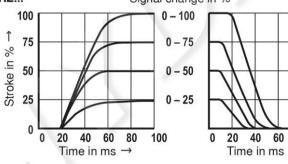


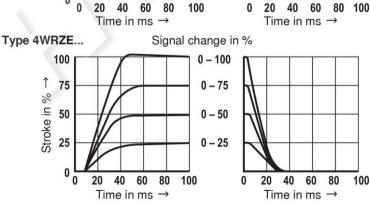
- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100 \text{ bar, constant}$

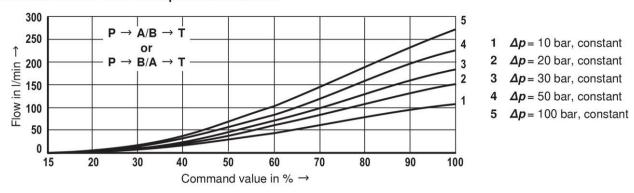
 Δp = valve pressure differential according to DIN 24311 (inlet pressure $p_{\rm p}$ minus load pressure $p_{\rm L}$ minus return flow pressure $p_{\rm T}$)

Transition functions with stepped, electric input signals, measured at $p_{\rm St}$ = 50 bar

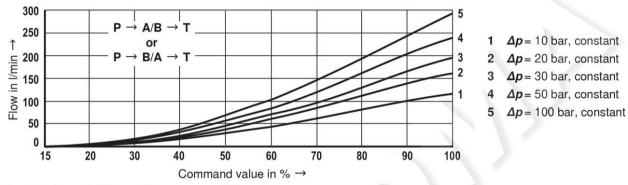




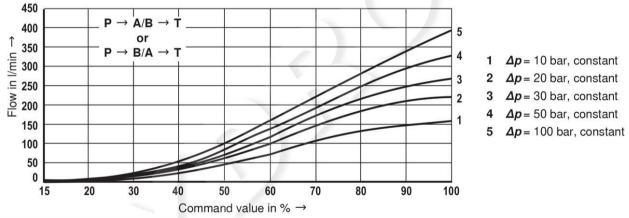




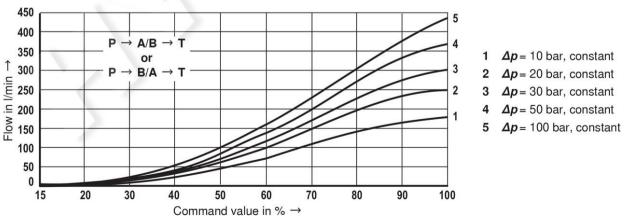
125 I/min rated flow at 10 bar valve pressure differential



150 I/min rated flow at 10 bar valve pressure differential

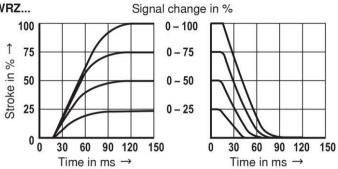


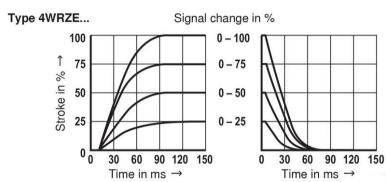
180 I/min rated flow at 10 bar valve pressure differential

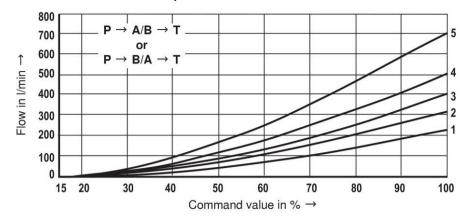


 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_p minus load pressure p_t minus return flow pressure p_T)

Transition functions with stepped, electric input signals, measured at $p_{\rm St}$ = 50 bar Type 4WRZ... Signal change in %

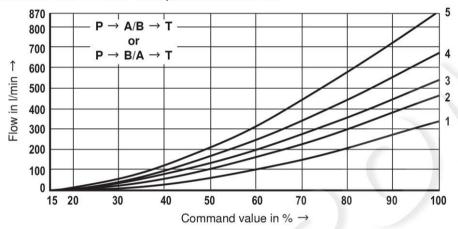






- 1 $\Delta p = 10$ bar, constant
- 2 $\Delta p = 20$ bar, constant
- 3 $\Delta p = 30$ bar, constant
- 4 $\Delta p = 50$ bar, constant
- 5 $\Delta p = 100$ bar, constant

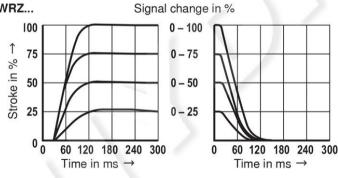
325 I/min rated flow at 10 bar valve pressure differential

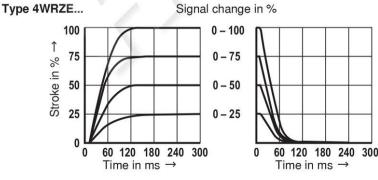


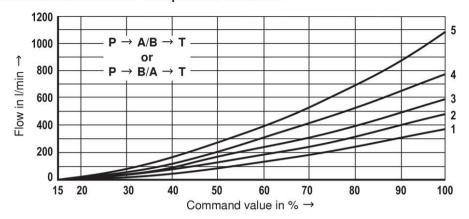
- 1 $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30 \text{ bar, constant}$
- 4 $\Delta p = 50$ bar, constant
- 5 $\Delta p = 100$ bar, constant

 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_p minus load pressure p_p minus return flow pressure p_T)

Transition functions with stepped, electric input signals, measured at p_{St} = 50 bar Type 4WRZ... Signal change in %

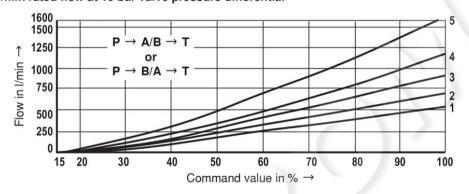






- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

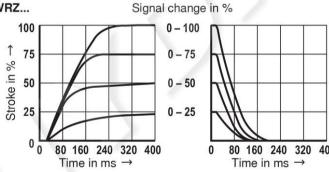
520 I/min rated flow at 10 bar valve pressure differential

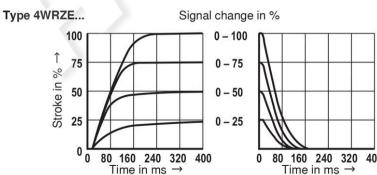


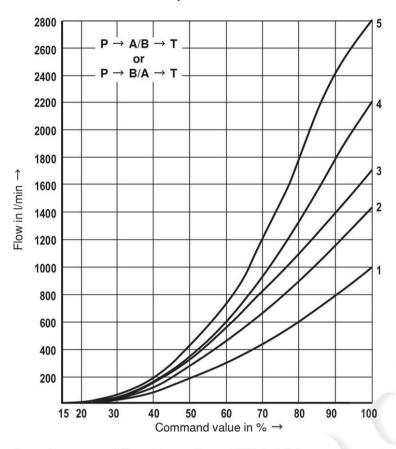
- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_p minus load pressure p_T minus return flow pressure p_T)

Transition functions with stepped, electric input signals, measured at $p_{\rm St}$ = 50 bar Type 4WRZ... Signal change in %



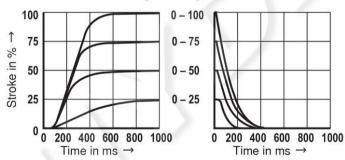


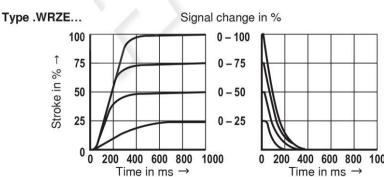


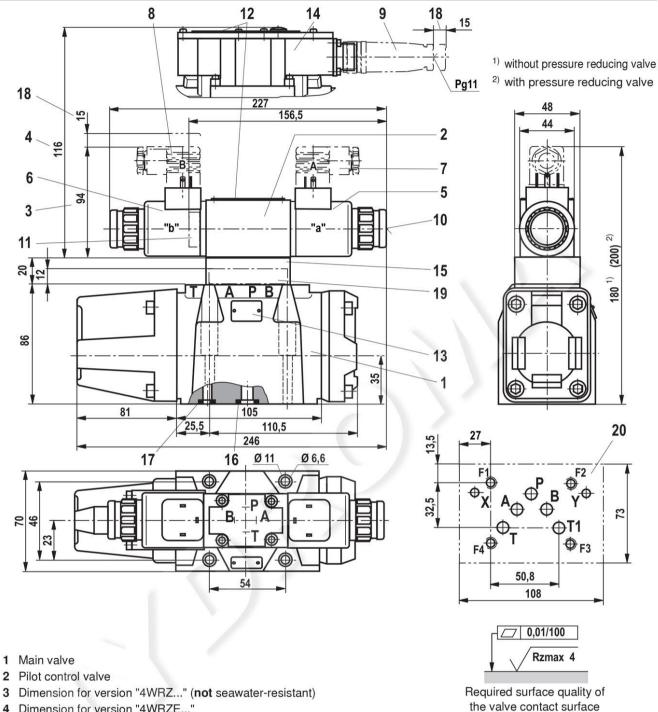
- 1 $\Delta p = 10$ bar, constant
- 2 $\Delta p = 20$ bar, constant
- 3 $\Delta p = 30$ bar, constant
- 4 $\Delta p = 50$ bar, constant
- 5 $\Delta p = 100$ bar, constant

 Δp = valve pressure differential according to DIN 24311 (inlet pressure $p_{\rm p}$ minus load pressure $p_{\rm i}$ minus return flow pressure $p_{\rm r}$)

Transition functions with stepped, electric input signals, measured at $p_{\rm St}$ = 50 bar Type .WRZ... Signal change in %

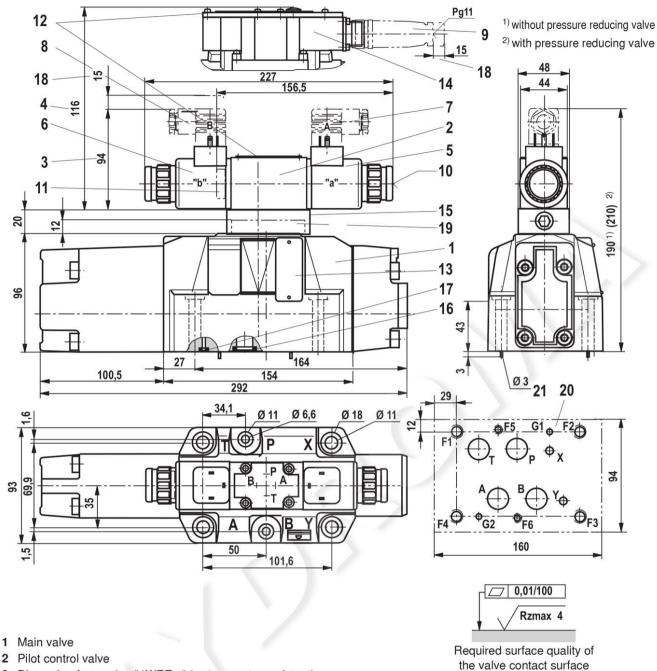






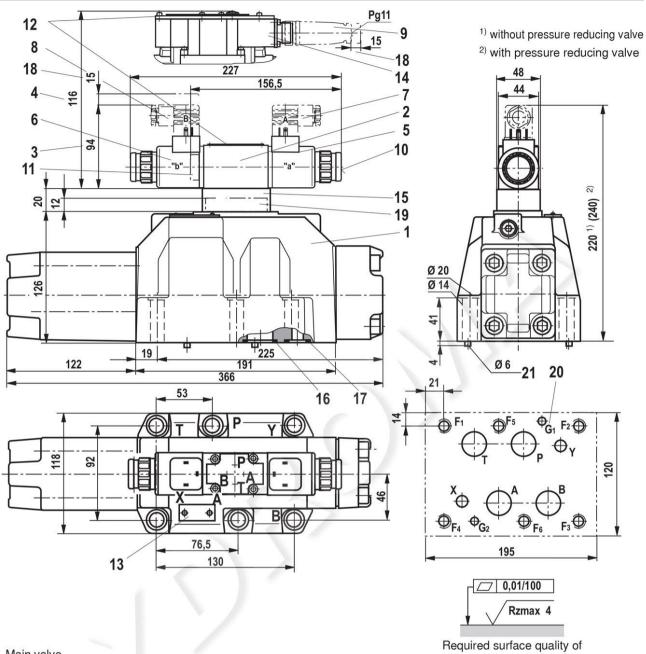
- 4 Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, T, and T1
- 17 Identical seal rings for ports X and Y
- 18 Space required to remove the mating connector
- 19 Diversion plate (type 4WRH...)
- 20 Machined installation surface, porting pattern according to ISO 4401-05-05-0-05, ports X and Y as required



- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, and T
- 17 Identical seal rings for ports X and Y
- 18 Space required to remove the mating connector
- 19 Diversion plate (type 4WRH...)
- 20 Machined installation surface, porting pattern according to ISO 4401-07-07-0-05, ports X and Y as required deviating from the standard: Ports A, B, P, T Ø20 mm.
- 21 Locking pin

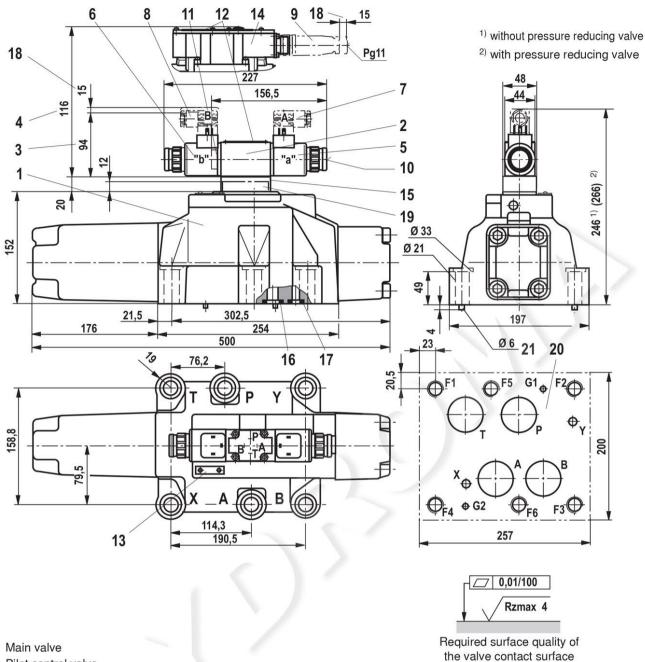


- 1 Main valve
- 2 Pilot control valve
- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- 4 Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, and T
- Identical seal rings for ports X and Y 17
- 18 Space required for removing the mating connector
- 19 Diversion plate (type 4WRH...)
- 20 Machined installation surface, porting pattern according to ISO 4401-08-08-0-05, ports X and Y as required

the valve contact surface

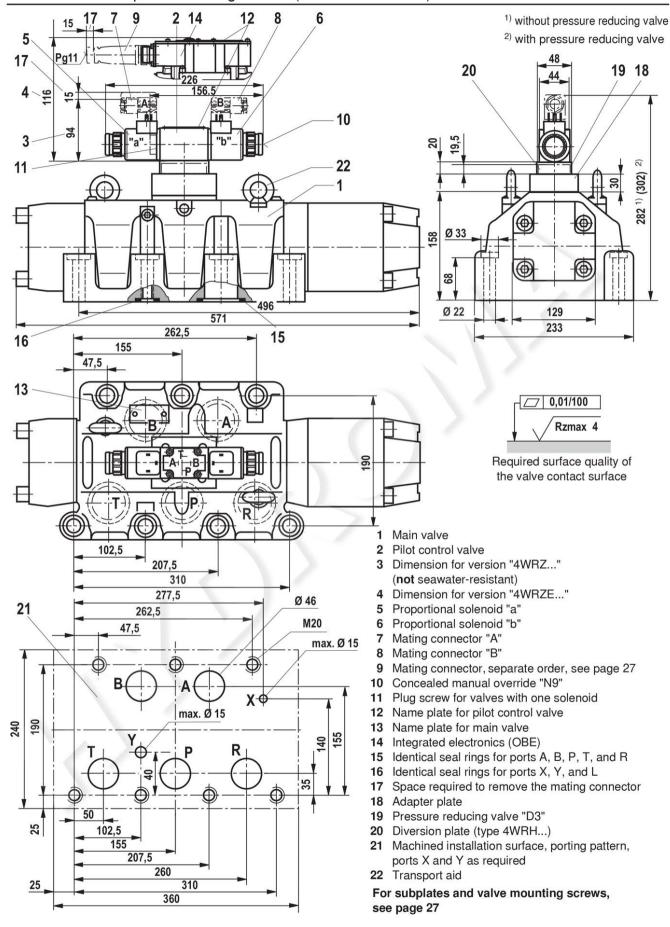
21 Locking pin



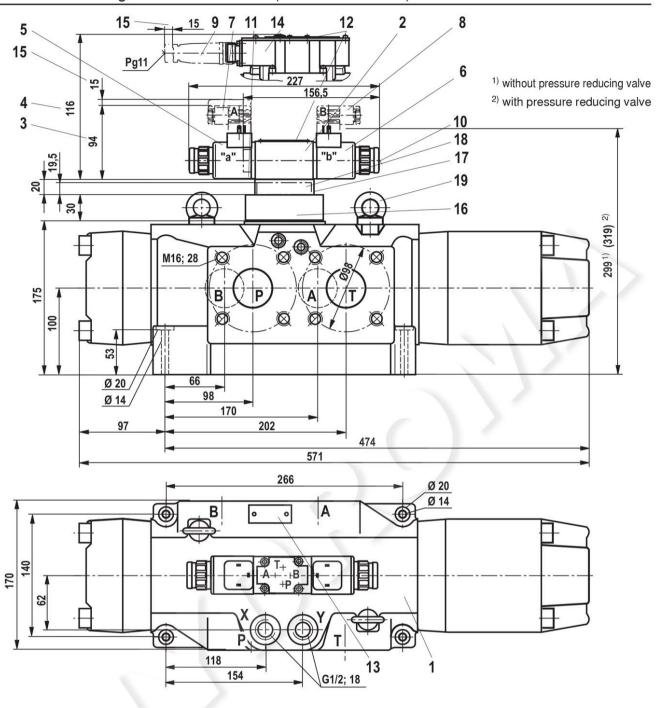
- 1 Main valve
- 2 Pilot control valve
- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, and T
- 17 Identical seal rings for ports X and Y
- 18 Space required for removing the mating connector
- 19 Diversion plate (type 4WRH...)
- Machined installation surface, porting pattern according to ISO 4401-10-09-0-05, ports X and Y as required deviating from the standard:
 - Ports A, B, T and P Ø38 mm.
- 21 Locking pin

For subplates and valve mounting screws, see page 27



Dimensions: Flange connection size 52 (dimensions in mm)



- 1 Main valve
- 2 Pilot control valve
- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- 4 Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"

- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)
- 15 Space required to remove the mating connector
- 16 Adapter plate
- 17 Pressure reducing valve "D3"
- 18 Diversion plate (type 4WRH...)
- 19 Transport aid

For subplates and valve mounting screws, see page 27

Accessories (not included in the scope of delivery)

| Mating connectors | | | Material number |
|----------------------------|-------------------|---------------------|---------------------------|
| Mating connector for 4WRZ | DIN EN 175301-803 | Solenoid "a", grey | R901017010 |
| | | Solenoid "b", black | R901017011 |
| Mating connector for 4WRZE | DIN EN 175201-804 | | e.g. R900021267 (plastic) |
| and 4WRZEJ | | | e.g. R900223890 (metal) |

| Hexagon socket head | d cap screws | Material number |
|---------------------|--|--------------------------|
| Size 10 | 4x ISO 4762 - M6 x 45 - 10.9-flZn-240h-L Tightening torque $M_{\rm A}$ = 13.5 Nm ±10% or 4x ISO 4762 - M6 x 45 - 10.9 Tightening torque $M_{\rm A}$ = 15.5 Nm ±10% | R913000258 |
| Size 16 | 2x ISO 4762 - M6 x 60 - 10.9-flZn-240h-L Tightening torque $\emph{M}_{\rm A}$ = 12.2 Nm ±10% 4x ISO 4762 - M10 x 60 - 10.9-flZn-240h-L Tightening torque $\emph{M}_{\rm A}$ = 58 Nm ±20% or 2x ISO 4762 - M6 x 60 - 10.9 Tightening torque $\emph{M}_{\rm A}$ = 15.5 Nm ±10% 4x ISO 4762 - M10 x 60 - 10.9 Tightening torque $\emph{M}_{\rm A}$ = 75 Nm ±20% | R913000115 R913000116 |
| Size 25 | 6x ISO 4762 - M12 x 60 - 10.9-flZn-240h-L Tightening torque M_A = 100 Nm ±20% or 6x ISO 4762 - M12 x 60 - 10.9 Tightening torque M_A = 130 Nm ±20% | R913000121 |
| Size 32 | 6x ISO 4762 - M20 x 80 - 10.9-flZn-240h-L Tightening torque $M_{\rm A}$ = 340 Nm ±20% or 6x ISO 4762 - M20 x 80 - 10.9 Tightening torque $M_{\rm A}$ = 430 Nm ±20% | R901035246 |
| Size 52 (5WRZ52) | With a steel installation surface: $7x \text{ ISO } 4762 \cdot \text{M20} \times 90 \cdot 10.9 \cdot \text{flZn-240h-L}$ Tightening torque $\textit{M}_{A} = 465 \text{ Nm } \pm 20\%$ With a cast iron installation surface: $7x \text{ ISO } 4762 \cdot \text{M20} \times 100 \cdot 10.9 \cdot \text{flZn-240h-L}$ Tightening torque $\textit{M}_{A} = 465 \text{ Nm } \pm 20\%$ or With a steel installation surface: $7x \text{ ISO } 4762 \cdot \text{M20} \times 90 \cdot 10.9$ Tightening torque $\textit{M}_{A} = 610 \text{ Nm } \pm 20\%$ With a cast iron installation surface: $7x \text{ ISO } 4762 \cdot \text{M20} \times 100 \cdot 10.9$ Tightening torque $\textit{M}_{A} = 610 \text{ Nm } \pm 20\%$ | R913000397 R913000386 |
| Size 52 (4WRZ52) | 4x ISO 4762 - M12 x 70 - 10.9-flZn-240h-L Tightening torque $M_{\rm A}$ = 100 Nm ±20% or 4x ISO 4762 - M12 x 70 - 10.9 Tightening torque $M_{\rm A}$ = 130 Nm ±20% | R913000515 |

When using type 4WRZ..., use the following throttle inserts in channel A and B of the pilot control valve:

| Data sheet |
|------------|
| 45054 |
| 45056 |
| 45058 |
| 45060 |
| 45501 |
| |

| Ø in mm | Material number |
|---------|-----------------|
| 1.8 | R900158510 |
| 2.0 | R900158547 |
| 2.8 | R900157948 |
| 3 | 8 |
| = | |
| | 1.8 |